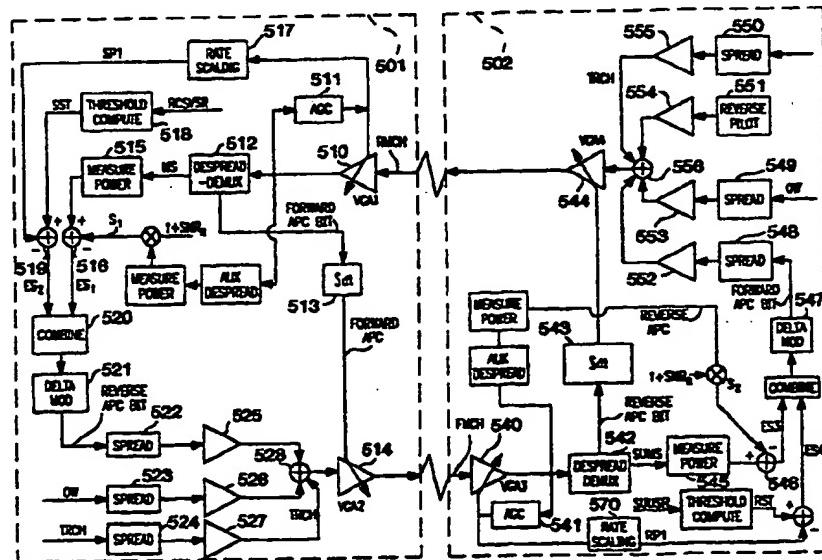




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<p>(54) Title: AUTOMATIC POWER CONTROL SYSTEM FOR A CODE DIVISION MULTIPLE ACCESS (CDMA) COMMUNICATIONS SYSTEM</p> <p>(57) Abstract</p> <p>An automatic power control (APC) system for a spread-spectrum communications system includes an automatic forward power control (AFPC) system, and an automatic reverse power control (ARPC) system. In the AFPC, each subscriber unit (SU) measures a forward signal-to-noise ratio of a respective forward channel information signal to generate a respective forward channel error signal which includes a measure of the uncorrelated noise in the channel and a measure of the error between the respective forward signal-to-noise ration and a pre determined signal-to-noise value. A control signal generated from the respective forward channel error signal is transmitted as part of a respective reverse channel information signal. A base unit includes AFPC receivers which receive respective reverse channel information signals and extract the forward channel error signals therefrom to adjust the power levels of the respective forward spread-spectrum signals. In the ARPC system, each base measures a reverse signal-to-noise ratio of each of the respective reverse channel information signals and generates a respective reverse channel error signal which includes a measure of the uncorrelated noise in the channel and a measure of the error between the respective reverse signal-to-noise ratio and a pre determined signal-to-noise value. The base unit transmits a control signal generated from the respective reverse channel error signal as a part of a respective forward channel information signal. Each SU includes an ARPC receiver which receives the forward channel information signal and extracts the respective reverse error signal to adjust the reverse transmit power level of the respective reverse spread-spectrum signal.</p>			



The diagram illustrates the internal components and signal flow of the automatic power control system. The forward path (501) starts with a forward APC section (510) containing a VCA, followed by a rate scaling block (517) and a threshold compute block (515). The reverse path (502) starts with a reverse APC section (544) containing a VCA, followed by a rate scaling block (550) and a threshold compute block (551). Both paths include measure power blocks (516 and 552) and despreading blocks. The system also features various control and feedback loops involving error signal processing and delta modulators.

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AUTOMATIC POWER CONTROL SYSTEM FOR A CODE DIVISION MULTIPLE ACCESS (CDMA) COMMUNICATIONS SYSTEM

BACKGROUND OF THE INVENTION

Providing quality telecommunication services to user groups which are classified as remote, such as rural telephone systems and telephone systems in developing countries, has proved to be a challenge over recent years. These needs have been partially satisfied by wireless radio services, such as fixed or mobile frequency division multiplex (FDM), frequency division multiple access (FDMA), time division multiplex (TDM), time division multiple access (TDMA) systems, combination frequency and time division systems (FD/TDMA), and other land mobile radio systems. Usually, these remote services are faced with more potential users than can be supported simultaneously by their frequency or spectral bandwidth capacity.

Recognizing these limitations, recent advances in wireless communications have used spread spectrum modulation techniques to provide simultaneous communication by multiple users through a single communications channel. Spread spectrum modulation refers to modulating a information signal with a spreading code signal; the spreading code signal being generated by a code generator where the period T_c of the spreading code is substantially less than the period of the information data bit or symbol signal. The code may modulate the carrier frequency upon which the information has been sent, called frequency-hopped spreading, or may directly modulate the signal by multiplying the spreading code with the information data signal, called direct-sequence spreading (DS). Spread-spectrum modulation produces a signal having a bandwidth that is substantially greater than that required to transmit the information signal. Synchronous reception and despreading of the signal at the receiver demodulator recovers the original information. The synchronous demodulator uses a reference signal to synchronize the despreading circuits to the input spread-spectrum modulated signal to recover the carrier and

information signals. The reference signal can be a spreading code which is not modulated by an information signal.

5 Spread-spectrum modulation in wireless networks offers many advantages because multiple users may use the same frequency band with minimal interference to each user's receiver. In addition, spread spectrum modulation reduces effects from other sources of interference. Also, synchronous spread-spectrum modulation and demodulation techniques may be expanded by providing multiple message channels for a user, each spread with a different spreading code, while still transmitting only a single reference signal to the user.

10 Another problem associated with multiple access, spread-spectrum communication systems is the need to reduce the total transmitted power of users in the system, since users may have limited available power. An associated problem requiring power control in spread-spectrum systems is related to the inherent characteristic of spread-spectrum systems that one user's spread-spectrum signal is received by another user as noise with a certain power level. Consequently, users transmitting with high levels of signal power may interfere with other users' reception. Also, if a user moves relative to another user's geographic location, signal fading and distortion require that the users adjust their transmit power level to maintain a particular signal quality, and to maintain the power that the base station receives from all users. Finally, because it is possible for the spread-spectrum system to have more remote users than can be supported simultaneously, the power control system should also employ a capacity management method which rejects additional users when the maximum system power level is reached.

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25 Prior spread-spectrum systems have employed a base station that measures a received signal and sends an adaptive power control (APC) signal to the remote users. Remote users include a transmitter with an automatic gain control (AGC) circuit which responds to the APC signal. In such systems the base station monitors the overall system power or the power received from each user, and sets the APC signal accordingly. This open loop system performance may be improved by including a measurement of the signal power received by the remote user from the base station, and transmitting an APC signal back to the base station to effectuate a closed loop power control method.

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These power control systems, however, exhibit several disadvantages. First, the base station must perform complex power control algorithms, increasing the amount of processing in the base station. Second, the system actually experiences several types of power variation: variation in the noise power caused by changing numbers of users and variations in the received signal power of a particular bearer channel. These variations occur with different frequency, so simple power control algorithms can be optimized only to one of the two types of variation. Finally, these power algorithms tend to drive the overall system power to a relatively high level. Consequently, there is a need for a spread-spectrum power control method that rapidly responds to changes in bearer channel power levels, while simultaneously making adjustments to all users' transmit power in response to changes in the number of users. Also, there is a need for an improved spread-spectrum communication system employing a closed loop power control system which minimizes the system's overall power requirements while maintaining a sufficient BER at the individual remote receivers. In addition, such a system should control the initial transmit power level of a remote user and manage total system capacity.

SUMMARY OF THE INVENTION

The present invention includes a system and method for closed loop automatic power control (APC) for a base radio carrier station (RCS) and a group of subscriber units (SUs) of a spread-spectrum communication system. The SUs transmit spread-spectrum signals, the RCS acquires the spread-spectrum signals, and the RCS detects the received power level of the spread-spectrum signals plus any interfering signal including noise. The APC system includes the RCS and a plurality of SUs, wherein the RCS transmits a plurality of forward channel information signals to the SUs as a plurality of forward channel spread-spectrum signals having a respective forward transmit power level, and each SU transmits to the base station at least one reverse spread-spectrum signal having a respective reverse transmit power level and at least one reverse channel spread-spectrum signal includes a reverse channel information signal.

The APC includes an automatic forward power control (AFPC) system, and an automatic reverse power control (ARPC) system. The AFPC has the steps of each SU measuring a forward signal-to-noise ratio of the respective forward channel information

signal, generating a respective forward channel error signal which includes a measure of the forward error between the respective forward signal-to-noise ratio and a pre-determined signal-to-noise value. The forward channel error signal also includes a measure of the uncorrelated noise in the channel. The respective forward channel error signal is transmitted by the SU as part of a respective reverse channel information signal. The RCS includes a plural number of AFPC receivers for receiving the reverse channel information signals and extracting the forward channel error signals from the respective reverse channel information signals. The RCS also adjusts the respective forward transmit power level of each one of the respective forward spread-spectrum signals responsive to the respective forward error signal.

The portion of the ARPC system in the RCS measures a reverse signal-to-noise ratio of each of the respective reverse channel information signals, generates a respective reverse channel error signal which includes a measure of the error between the respective reverse channel signal-to-noise ratio and a respective pre-determined signal-to-noise value. The reverse channel error signal also includes a measure of the uncorrelated noise in the channel. The RCU transmits the respective reverse channel error signal as a part of a respective forward channel information signal. Each SU includes an ARPC receiver which receives the forward channel information signal, extracts the respective reverse error signal from the forward channel information signal, and adjusts the reverse transmit power level of the respective reverse spread-spectrum signal responsive to the respective reverse error signal.

BRIEF DESCRIPTION OF THE DRAWINGS

Figure 1 is a block diagram of a code division multiple access communication system according to the present invention.

Figure 2 is a flow-chart diagram of an exemplary maintenance power control algorithm of the present invention.

Figure 3 is a flow-chart diagram of an exemplary automatic forward power control algorithm of the present invention.

Figure 4 is a flow-chart diagram of an exemplary automatic reverse power control algorithm of the present invention.

Figure 5 is a block diagram of an exemplary closed loop power control system of the present invention when the bearer channel is established.

5 Figure 6 is a block diagram of an exemplary closed loop power control system of the present invention during the process of establishing the bearer channel.

DESCRIPTION OF THE EXEMPLARY EMBODIMENT

The system of the present invention provides local-loop telephone service using radio link between one or more base stations and multiple remote subscriber units.

10 In the exemplary embodiment, one radio link is described for a base station communicating with a fixed subscriber unit (FSU), but the system is equally applicable to systems including multiple base stations with radio links to both FSUs and Mobile Subscriber Units (MSUs). Consequently, the remote subscriber units are referred to herein as Subscriber Units (SUs).

15 Referring to Figure 1, Base Station (BS) 101 provides call connection to a local exchange (LE) 103 or any other telephone network switching interface, and includes a Radio Carrier Station (RCS) 104. One or more RCSs 104, 105, 110 connect to a Radio Distribution Unit (RDU) 102 through links 131, 132, 137, 138, 139, and RDU 102 interfaces with LE 103 by transmitting and receiving call set-up, control, and information signals through telco links 141, 142, 150. SUs 116, 119 communicate with the RCS 104 through RF links 161, 162, 163, 164, 165. Alternatively, another embodiment of the 20 invention includes several SUs and a "master" SU with functionality similar to the RCS. Such an embodiment may or may not have connection to a local telephone network.

25 Although the described embodiment uses different spread-spectrum bandwidths centered around a carrier for the transmit and receive spread-spectrum channels, the present method is readily extended to systems using multiple spread-spectrum bandwidths for the transmit channels and multiple spread-spectrum bandwidths for the receive channels. Alternatively, because spread-spectrum communication systems have the inherent feature that one user's transmission appears as noise to another user's

despread receiver, an embodiment can employ the same spread-spectrum channel for both the transmit and receive path channels. In other words, Uplink and Downlink transmissions can occupy the same frequency band. An embodiment of the invention may also employ multiple spread spectrum channels which need not be adjacent in frequency.

5 In this embodiment, any channel may be used for Uplink, Downlink or Uplink and Downlink transmission.

In the exemplary embodiment, the spread binary symbol information is transmitted over the radio links 161 to 165 using Quadrature Phase Shift Keying (QPSK) modulation with Nyquist Pulse Shaping, although other modulation techniques may be used, including, but not limited to, Offset QPSK (OQPSK), Minimum Shift Keying (MSK), M-ary Phase Shift Keying (MPSK) and Gaussian Phase Shift Keying (GPSK).

The CDMA demodulator in either the RCS or the SU despreads the received signal with appropriate processing to combat or exploit multipath propagation effects. Parameters concerning the received power level are used to generate the

10 Automatic Power Control (APC) information which, in turn, is transmitted to the other end. The APC information is used to control transmit power of the automatic forward power control (AFPC) and automatic reverse power control (ARPC) links. In addition, each RCS 104, 105 and 110 can perform Maintenance Power Control (MPC), in a manner similar to APC, to adjust the initial transmit power of each SU 111, 112, 115,

15 20 117 and 118. Demodulation is coherent where the pilot signal provides the phase reference.

The transmit power levels of the radio interface between RCS 104 and SUs 111, 112, 115, 117 and 118 are controlled using two different closed loop power control algorithms. The Automatic Forward Power Control (AFPC) determines the Downlink transmit power level, and the Automatic Reverse Power Control (ARPC) determines the Uplink transmit power level. The logical control channel by which SU 111 and RCS 104, for example, transfer power control information operates at least a 16 kHz update rate. Other embodiments may use a faster 32 kHz update rate. These algorithms ensure that the transmit power of a user maintains an acceptable Bit-Error Rate (BER), maintains the

system power at a minimum to conserve power, and maintains the power level of all SUs 111, 112, 115, 117 and 118, as received by RCS 104, at a nearly equal level.

In addition, the system includes an optional maintenance power algorithm that is used during the inactive mode of a SU. When SU 111 is inactive or powered-down to conserve power, the unit may occasionally activate itself and adjust its initial transmit power level setting in response to a maintenance power control signal from RCS 104. The maintenance power signal is determined by the RCS 104 by measuring the received power level of SU 111 and present system power level and calculating the necessary initial transmit power. The method shortens the channel acquisition time of SU 111 when it is turned on to begin a communication. The method also prevents the transmit power level of SU 111 from becoming too high and interfering with other channels during the initial transmission before the closed loop power control adjusts the transmit power to a level appropriate for the other message traffic in the channel.

The RCS 104 obtains synchronization of its clock from an interface line such as, but not limited to, E1, T1, or HDSL interfaces. Each RCS can also generate its own internal clock signal from an oscillator which may be regulated by a Global Positioning System (GPS) receiver. The RCS 104 generates a Global Pilot Code for a channel having a spreading code but no data modulation, which can be acquired by remote SUs 111 through 118. All transmission channels of the RCS are synchronous with the Pilot channel, and spreading code phases of code generators (not shown) used for Logical communication channels within RCS 104 are also synchronous with the Pilot channel's spreading code phase. Similarly, SUs 111 through 118 which receive the Global Pilot Code of RCS 104 synchronize the spreading and de-spreading code phases of the code generators (not shown) of the SUs to the Global Pilot Code.

25 Logical Communication Channels

A 'channel' of the prior art is usually regarded as a communications path that is part of an interface and that can be distinguished from other paths of the interface without regard to its content. In the case of CDMA, however, separate communications paths are distinguished only by their content. The term 'logical channel' is used to distinguish the separate data streams, which are logically equivalent to channels in the

conventional sense. All logical channels and sub-channels of the present invention are mapped to a common 64 kilo-symbols per second (ksym/s) QPSK stream. Some channels are synchronized to associated pilot codes which are generated and perform a similar function to the system Global Pilot Code. The system pilot signals are not, however, considered logical channels.

Several logical communication channels are used over the RF communication link between the RCS and SU. Each logical communication channel either has a fixed, pre-determined spreading code or a dynamically assigned spreading code. For both pre-determined and assigned codes, the code phase is synchronous with the Pilot Code. Logical communication channels are divided into two groups: the Global Channel (GC) group and the Assigned Channel (AC) group. The GC group includes channels which are either transmitted from the base station RCS to all the remote SUs or from any SU to the RCS of the base station regardless of the SU's identity. These channels typically contain information of a given type for all users. These channels include the channels used by the SUs to gain system access. Channels in the Assigned Channels (AC) group are those channels dedicated to communication between the RCS and a particular SU.

20 POWER CONTROL

General

The power control feature of the present invention is used to minimize the transmit power used between an RCS and any SUs with which it is in communication. The power control subfeature that updates transmit power during bearer channel connection is defined as automatic power control (APC). APC data is transferred from the RCS to an SU on the forward APC channel and from an SU to the RCS on the reverse APC channel. When there is no active data link between the two, the maintenance power control subfeature (MPC) controls the transmit power of the SU.

Transmit power levels of forward and reverse assigned channels and reverse global channels are controlled by the APC algorithm to maintain sufficient signal power to interference noise power ratio (SIR) on those channels, and to stabilize and minimize system output power. The present invention uses a closed loop power control system in which a receiver controls its associated transmitter to incrementally raise or lower its transmit power. This control is conveyed to the associated transmitter via the power control signal on the APC channel. The receiver makes the decision to increase or decrease the transmitter's power based on two error signals. One error signal is an indication of the difference between the measured and required despread signal powers, and the other error signal is an indication of the average received total power.

As used in the described embodiment of the invention, the term *near-end* power control is used to refer to adjusting the transmitter's output power in accordance with the APC signal received on the APC channel from the other end. This means the reverse power control for the SU and forward power control for the RCS; and the term *far-end* APC is used to refer to forward power control for the SU and reverse power control for the RCS (adjusting the transmit power of the unit at the opposite end of the channel).

In order to conserve power, the SU modem terminates transmission and powers-down while waiting for a call, defined as the sleep phase. Sleep phase is terminated by an awaken signal from the SU controller. Responsive to this signal, the SU modem acquisition circuit automatically enters the reacquisition phase, and begins the process of acquiring the downlink pilot, as described below.

Closed Loop Power Control Algorithms

The near-end power control includes two steps: first, set the initial transmit power; second, continually adjust transmit power according to information received from the far-end using APC.

For the SU, initial transmit power is set to a minimum value and then ramped up, for example, at a rate of 1 dB/ms until either a ramp-up timer expires (not shown) or the RCS changes the corresponding traffic light value on the FBCH to "red" indicating the RCS has locked to the SU's short pilot signal (SAXPT). Expiration of the timer causes the SAXPT transmission to be shut down, unless the traffic light value is set to red first,

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in which case the SU continues to ramp-up transmit power but at a much lower rate than before the "red" signal was detected.

For the RCS, initial transmit power is set at a fixed value, corresponding to the minimum value necessary for reliable operation as determined experimentally for the service type and the current number of system users. Global channels, such as the Global Pilot or, the fast broadcast channel (FBCH), are always transmitted at the fixed initial power, whereas traffic channels are switched to APC.

The APC signal is transmitted as one bit signals on the APC channel. The one-bit signal represents a command to increase (signal is logic-high) or decrease (signal is logic-low) the associated transmit power. In the described embodiment, the 64 kbps APC data stream is not encoded or interleaved.

Far-end power control consists of the near-end transmitting power control information for the far-end to use in adjusting its transmit power.

The APC algorithm causes the RCS or the SU to transmit +1 if the following inequality holds, otherwise -1 (logic-low).

$$\alpha_1 e_1 - \alpha_2 e_2 > 0 \quad (1)$$

Here, the error signal e_1 is calculated as

$$e_1 = P_d - (1 + SNR_{REF}) P_N \quad (2)$$

where P_d is the despread signal plus noise power, P_N is the despread noise power, and SNR_{REF} is the desired despread signal to noise ratio for the particular service type; and

$$e_2 = P_r - P_o \quad (3)$$

where P_r is a measure of the received power and P_o is the automatic gain control (AGC) circuit set point. The weights α_1 and α_2 in equation (30) are chosen for each service type and for the APC update rate.

25 Maintenance Power Control

During the sleep phase of the SU, the interference noise power of the CDMA RF channel changes. As an alternative to the initial power ramp-up method described above, the present invention may include a maintenance power control feature (MPC) which

periodically adjusts the SU's initial transmit power with respect to the interference noise power of the CDMA channel. The MPC is the process whereby the transmit power level of an SU is maintained within close proximity of the minimum level required for the RCS to detect the SU's signal. The MPC process compensates for low frequency changes in the required SU transmit power.

The maintenance control feature uses two global channels: one is called the status channel (STCH) on reverse link, and the other is called the check-up channel (CUCH) on forward link. The signals transmitted on these channels carry no data and they are generated the same way the short codes used in initial power ramp-up are generated. The STCH and CUCH codes are generated from a "reserved" branch of the global code generator.

The MPC process is as follows. At random intervals, the SU sends a symbol length spreading code periodically for 3 ms on the status channel (STCH). If the RCS detects the sequence, it replies by sending a symbol length code sequence within the next 3 ms on the check-up channel (CUCH). When the SU detects the response from the RCS, it reduces its transmit power by a particular step size. If the SU does not detect any response from the RCS within the 3 ms period, it increases its transmit power by the step size. Using this method, the RCS response is transmitted at a power level that is enough to maintain a 0.99 detection probability at all SU's.

The rate of change of traffic load and the number of active users is related to the total interference noise power of the CDMA channel. The update rate and step size of the maintenance power update signal for the present invention is determined by using queuing theory methods well known in the art of communication theory. By modeling the call origination process as an exponential random variable with mean 6.0 mins, numerical computation shows the maintenance power level of a SU should be updated once every 10 seconds or less to be able to follow the changes in interference level using 0.5 dB step size. Modeling the call origination process as a Poisson random variable with exponential interarrival times, arrival rate of 2×10^4 per second per user, service rate of 1/360 per second, and the total subscriber population is 600 in the RCS service area also yields by

numerical computation that an update rate of once every 10 seconds is sufficient when 0.5 dB step size is used.

5 Maintenance power adjustment is performed periodically by the SU which changes from sleep phase to awake phase and performs the MPC process. Consequently, the process for the MPC feature is shown in Figure 2 and is as follows: First, at step 201, signals are exchanged between the SU and the RCS maintaining a transmit power level that is close to the required level for detection: the SU periodically sends a symbol length spreading code in the STCH, and the RCS sends periodically a symbol length spreading code in the CUCH as response.

10 Next, at step 202, if the SU receives a response within 3 ms after the STCH message it sent, it decreases its transmit power by a particular step size at step 203; but if the SU does not receive a response within 3 ms after the STCH message, it increases its transmit power by the same step size at step 204.

15 The SU waits, at step 205, for a period of time before sending another STCH message, this time period is determined by a random process which averages 10 seconds.

Thus, the transmit power of the STCH messages from the SU is adjusted based on the RCS response periodically, and the transmit power of the CUCH messages from the RCS is fixed.

20 **Mapping of Power Control Signal to Logical Channels For APC**

Power control signals are mapped to specified Logical Channels for controlling transmit power levels of forward and reverse assigned channels. Reverse global channels are also controlled by the APC algorithm to maintain sufficient signal power to interference noise power ratio (SIR) on those reverse channels, and to stabilize and minimize system output power. The present invention uses a closed loop power control method in which a receiver periodically decides to incrementally raise or lower the output power of the transmitter at the other end. The method also conveys that decision back to the respective transmitter.

Table 1: APC Signal Channel Assignments

<u>Link</u> Channels and Signals	Call/Connection Status	Power Control Method	
		Initial Value	Continuous
<u>Reverse link</u> AXCH AXPT	Being Established	as determined by power ramping	APC bits in forward APC channel
<u>Reverse link</u> APC, OW, TRCH, pilot signal	In-Progress	level established during call set-up	APC bits in forward APC channel
<u>Forward link</u> APC, OW, TRCH	In-Progress	fixed value	APC bits in reverse APC channel

Forward and reverse links are independently controlled. For a call/connection in process, forward link traffic channel (TRCH) APC, and Order Wire (OW) power is controlled by the APC bits transmitted on the reverse APC channel. During the call/connection establishment process, reverse link access channel (AXCH) power is also controlled by the APC bits transmitted on the forward APC channel. Table 11 summarizes the specific power control methods for the controlled channels.

The required SIRs of the assigned channels TRCH, APC and OW and reverse assigned pilot signal for any particular SU are fixed in proportion to each other and these channels are subject to nearly identical fading, therefore, they are power controlled together.

Automatic Forward Power Control

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The AFPC system attempts to maintain the minimum required SIR on the forward channels during a call/connection. The AFPC recursive process shown in Figure 3 consists of the steps of having an SU form the two error signals e_1 and e_2 in step 301 where

$$e_1 = P_d - (1 + \text{SNR}_{\text{REF}}) P_N \quad (4)$$

$$e_2 = P_r - P_o \quad (5)$$

and P_d is the despread signal plus noise power, P_N is the despread noise power, SNR_{REF} is the required signal to noise ratio for the service type, P_r is a measure of the total received power, and P_o is the AGC set point. Next, the SU modem forms the combined error signal $\alpha_1 e_1 + \alpha_2 e_2$ in step 302. Here, the weights α_1 and α_2 are chosen for each service type and APC update rate. In step 303, the SU hard limits the combined error signal and forms a single APC bit. The SU transmits the APC bit to the RCS in step 304 and RCS modem receives the bit in step 305. The RCS increases or decreases its transmit power to the SU in step 306 and the algorithm repeats starting from step 301.

15 Automatic Reverse Power Control

The ARPC system maintains the minimum required SIR on the reverse channels to minimize the total system reverse output power, during both call/connection establishment and while the call/connection is in progress. The ARPC recursive process shown in Figure 4 begins at step 401 where the RCS modem forms the two error signals e_1 and e_2 in step 401 where

$$e_1 = P_d - (1 + \text{SNR}_{\text{REF}}) P_N \quad (6)$$

$$e_2 = P_n - P_o \quad (7)$$

and P_d is the despread signal plus noise power, P_N is the despread noise power, SNR_{REF} is the reference signal to noise ratio for the service type, P_n is a measure of the average total power received by the RCS, and P_o is the AGC set point. The RCS modem forms the combined error signal $\alpha_1 e_1 + \alpha_2 e_2$ in step 402 and hard limits this error signal to determine a single APC bit in step 403. The RCS transmits the APC bit to the SU in step 404, and the bit is received by the SU in step 405. Finally, SU adjusts its transmit power

according to the received APC bit in step 406, and the process repeats starting from step 401.

Table 2: Symbols/Thresholds Used for APC Computation

Service or Call Type	Call/Connection Status	Symbol (and Threshold) Used for APC Decision
Don't care	Being Established	AXCH
ISDN D SU	In-Progress	one 1/64-KBPS symbol from TRCH (ISDN-D)
ISDN 1B+D SU	In-Progress	TRCH (ISDN-B)
ISDN 2B+D SU	In-Progress	TRCH (one ISDN-B)
POTS SU (64 KBPS PCM)	In-Progress	one 1/64-KBPS symbol from TRCH, use 64 KBPS PCM threshold
POTS SU (32 KBPS ADPCM)	In-Progress	one 1/64-KBPS symbol from TRCH, use 32 KBPS ADPCM threshold
Silent Maintenance Call (any SU)	In-Progress	OW (continuous during a maintenance call)

SIR and Multiple Channel Types

The required SIR for channels on a link is a function of channel format (e.g. TRCH, OW), service type (e.g. ISDN B, 32 kb/s ADPCM POTS), and the number of symbols over which data bits are distributed (e.g. two 64 kb/s symbols are integrated to form a single 32 kb/s ADPCM POTS symbol). Despreader output power corresponding to the required SIR for each channel and service type is predetermined. While a call/connection is in progress, several user CDMA logical channels are concurrently active; each of these channels transfers a symbol every symbol period. The SIR of the symbol from the nominally highest SIR channel is measured, compared to a threshold and used to determine the APC step up/down decision each symbol period. Table 2 indicates the symbol (and threshold) used for the APC computation by service and call type.

APC Parameters

5 APC information is always conveyed as a single bit of information, and the APC Data Rate is equivalent to the APC Update Rate. The APC update rate is 64 kb/s. This rate is high enough to accommodate expected Rayleigh and Doppler fades, and allow for a relatively high (~0.2) Bit Error Rate (BER) in the Uplink and Downlink APC channels, which minimizes capacity devoted to the APC.

The power step up/down indicated by an APC bit is nominally between 0.1 and 0.01 dB. The dynamic range for power control is 70 dB on the reverse link and 12 dB on the forward link for the exemplary embodiment of the present system.

10 **An Alternative Embodiment for Multiplexing APC Information**

15 The dedicated APC and OW logical channels described previously can also be multiplexed together in one logical channel. The APC information is transmitted at 64 kb/s. continuously whereas the OW information occurs in data bursts. The alternative multiplexed logical channel includes the unencoded, non-interleaved 64 kb/s. APC information on, for example, the In-phase channel and the OW information on the Quadrature channel of the QPSK signal.

Closed Loop Power Control Implementation

20 The closed loop power control during a call connection responds to two different variations in overall system power. First, the system responds to local behavior such as changes in power level of an SU, and second, the system responds to changes in the power level of the entire group of active users in the system.

25 The Power Control system of the exemplary embodiment of the present invention is shown in Figure 5. As shown, the circuitry used to adjust the transmitted power is similar for the RCS (shown as the RCS power control module 501) and SU (shown as the SU power control module 502). Beginning with the RCS power control module 501, the reverse link RF channel signal is received at the RF antenna and demodulated to produce the reverse CDMA signal RMCH which is applied to the variable gain amplifier (VGA1) 510. The output signal of VGA1 510 is provided to the Automatic Gain Control (AGC)

5 Circuit 511 which produces a variable gain amplifier control signal into the VGA1 510. This signal maintains the level of the output signal of VGA1 510 at a near constant value. The output signal of VGA1 is despread by the despread-demultiplexer (demux) 512, which produces a despread user message signal MS and a forward APC bit. The forward APC bit is applied to the integrator 513 to produce the Forward APC control signal. The Forward APC control signal controls the Forward Link VGA2 514 and maintains the Forward Link RF channel signal at a minimum level necessary for communication.

10 The signal power of the despread user message signal MS of the RCS power module 501 is measured by the power measurement circuit 515 to produce a signal power indication. The output of the VGA1 is also despread by the AUX despreaders which despreads the signal by using an uncorrelated spreading code, and hence obtains a despread noise signal. The power measurement of this signal is multiplied by 1 plus the required signal to noise ratio (SNR_R) to form the threshold signal S1. The difference between the despread signal power and the threshold value S1 is produced by the 15 subtracter 516. This difference is the error signal ES1, which is an error signal relating to the particular SU transmit power level. Similarly, the control signal for the VGA1 510 is applied to the rate scaling circuit 517 to reduce the rate of the control signal for VGA1 510. The output signal of scaling circuit 517 is a scaled system power level signal SP1. The Threshold Compute logic 518 computes the System Signal Threshold SST value from 20 the RCS user channel power data signal (RCSUSR). The complement of the Scaled system power level signal, SP1, and the System Signal Power Threshold value SST are applied to the adder 519 which produces second error signal ES2. This error signal is related to the system transmit power level of all active SUs. The input Error signals ES1 and ES2 are combined in the combiner 520 produce a combined error signal input to the 25 delta modulator (DM1) 521, and the output signal of the DM1 is the reverse APC bit stream signal, having bits of value +1 or -1, which for the present invention is transmitted as a 64kb/sec signal.

30 The Reverse APC bit is applied to the spreading circuit 522, and the output signal of the spreading circuit 522 is the spread-spectrum forward APC message signal. Forward OW and Traffic signals are also provided to spreading circuits 523, 524, producing forward traffic message signals 1, 2, . . . N. The power level of the forward

APC signal, the forward OW, and traffic message signals are adjusted by the respective amplifiers 525, 526 and 527 to produce the power level adjusted forward APC, OW, and TRCH channels signals. These signals are combined by the adder 528 and applied to the VAG2 514, which produces forward link RF channel signal.

5 The forward link RF channel signal including the spread forward APC signal is received by the RF antenna of the SU, and demodulated to produce the forward CDMA signal FMCH. This signal is provided to the variable gain amplifier (VGA3) 540. The output signal of VGA3 is applied to the Automatic Gain Control Circuit (AGC) 541 which produces a variable gain amplifier control signal to VGA3 540. This signal
10 maintains the level of the output signal of VGA3 at a near constant level. The output signal of VAG3 540 is despread by the despread demux 542, which produces a despread user message signal SUMS and a reverse APC bit. The reverse APC bit is applied to the integrator 543 which produces the Reverse APC control signal. This reverse APC control signal is provided to the Reverse APC VGA4 544 to maintain the Reverse link RF
15 channel signal at a minimum power level.

The despread user message signal SUMS is also applied to the power measurement circuit 545 producing a power measurement signal, which is added to the complement of threshold value S2 in the adder 546 to produce error signal ES3. The signal ES3 is an error signal relating to the RCS transmit power level for the particular SU. To obtain
20 threshold S2, the despread noise power indication from the AUX despreaders is multiplied by 1 plus the desired signal to noise ratio SNR_R. The AUX despreaders despreads the input data using an uncorrelated spreading code, hence its output is an indication of the despread noise power.

Similarly, the control signal for the VGA3 is applied to the rate scaling circuit to
25 reduce the rate of the control signal for VGA3 in order to produce a scaled received power level RP1 (see Fig. 5). The threshold compute circuit computes the received signal threshold RST from SU measured power signal SUUSR. The complement of the scaled received power level RP1 and the received signal threshold RST are applied to the adder which produces error signal ES4. This error is related to the RCS transmit power to all
30 other SUs. The input error signals ES3 and ES4 are combined in the combiner and input

to the delta modulator DM2 547, and the output signal of DM2 547 is the forward APC bit stream signal, with bits having value of value +1 or -1. In the exemplary embodiment of the present invention, this signal is transmitted as a 64kb/sec signal.

The Forward APC bit stream signal is applied to the spreading circuit 2948, to produce the output reverse spread-spectrum APC signal. Reverse OW and Traffic signals are also input to spreading circuits 549, 550, producing reverse OW and traffic message signals 1, 2, . . N, and the reverse pilot is generated by the reverse pilot generator 551. The power level of the reverse APC message signal, reverse OW message signal, reverse pilot, and the reverse traffic message signals are adjusted by amplifiers 552, 553, 554, 555 to produce the signals which are combined by the adder 556 and input to the reverse APC VGA4 544. It is this VGA4 544 which produces the reverse link RF channel signal.

During the call connection and bearer channel establishment process, the closed loop power control of the present invention is modified, and is shown in Figure 6. As shown, the circuits used to adjust the transmitted power are different for the RCS, shown as the Initial RCS power control module 601; and for the SU, shown as the Initial SU power control module 602. Beginning with the Initial RCS power control module 601, the reverse link RF channel signal is received at the RF antenna and demodulated producing the reverse CDMA signal IRMCH which is received by the first variable gain amplifier (VGA1) 603. The output signal of VGA1 is detected by the Automatic Gain Control Circuit (AGC1) 604 which provides a variable gain amplifier control signal to VGA1 603 to maintain the level of the output signal of VAG1 at a near constant value. The output signal of VGA1 is despread by the despread demultiplexer 605, which produces a despread user message signal IMS. The Forward APC control signal, ISET, is set to a fixed value, and is applied to the Forward Link Variable Gain Amplifier (VGA2) 606 to set the Forward Link RF channel signal at a predetermined level.

The signal power of the despread user message signal IMS of the Initial RCS power module 601 is measured by the power measure circuit 607, and the output power measurement is subtracted from a threshold value S3 in the subtracter 608 to produce error signal ESS, which is an error signal relating to the transmit power level of a particular SU. The threshold S3 is calculated by multiplying the despread power

measurement obtained from the AUX despreader by 1 plus the desired signal to noise ratio SNR_R. The AUX despreader despreads the signal using an uncorrelated spreading code, hence its output signal is an indication of despread noise power. Similarly, the VGA1 control signal is applied to the rate scaling circuit 609 to reduce the rate of the 5 VGA1 control signal in order to produce a scaled system power level signal SP2. The threshold computation logic 610 determines an Initial System Signal Threshold value (ISST) computed from the user channel power data signal (IRCSUSR). The complement of the scaled system power level signal SP2 and the (ISST) are provided to the adder 611 which produces a second error signal ES6, which is an error signal relating to the system 10 transmit power level of all active SUs. The value of ISST is the desired transmit power for a system having the particular configuration. The input Error signals ES5 and ES6 are combined in the combiner 612 produce a combined error signal input to the delta modulator (DM3) 613. DM3 produces the initial reverse APC bit stream signal, having 15 bits of value +1 or -1, which for the present invention is transmitted as a 64kb/sec signal.

15 The Reverse APC bit stream signal is applied to the spreading circuit 614, to produce the initial spread-spectrum forward APC signal. The control channel (CTCH) information is spread by the spreader 616 to form the spread CTCH message signal. The spread APC and CTCH signals are scaled by the amplifiers 615 and 617, and combined by the combiner 618. The combined signal is applied to VAG2 606, which produces the 20 forward link RF channel signal.

25 The forward link RF channel signal including the spread forward APC signal is received by the RF antenna of the SU, and demodulated to produce the initial forward CDMA signal (IFMCH) which is applied to the variable gain amplifier (VGA3) 620. The output signal of VGA3 is detected by the Automatic Gain Control Circuit (AGC2) 621 which produces a variable gain amplifier control signal for the VGA3 620. This signal maintains the output power level of the VGA3 620 at a near constant value. The output signal of VAG3 is despread by the despread demultiplexer 622, which produces an initial reverse APC bit that is dependent on the output level of VGA3. The reverse APC bit is processed by the integrator 623 to produce the Reverse APC control signal. The Reverse 30 APC control signal is provided to the Reverse APC VGA4 624 to maintain Reverse link RF channel signal at a defined power level.

The global channel AXCH signal is spread by the spreading circuits 625 to provide the spread AXCH channel signal. The reverse pilot generator 626 provides a reverse pilot signal, and the signal power of AXCH and the reverse pilot signal are adjusted by the respective amplifiers 627 and 628. The spread AXCH channel signal and the reverse pilot signal are added by the adder 629 to produce reverse link CDMA signal. The reverse link CDMA signal is received by the reverse APC VGA4 624, which produces the reverse link RF channel signal output to the RF transmitter.

System Capacity Management

The system capacity management algorithm of the present invention optimizes the maximum user capacity for an RCS area, called a cell. When the SU comes within a certain value of maximum transmit power, the SU sends an alarm message to the RCS. The RCS sets the traffic lights which control access to the system, to "red" which, as previously described, is a flag that inhibits access by the SU's. This condition remains in effect until the alarming SU terminates its call, or until the transmit power of the alarming SU, measured at the SU, is a value less than the maximum transmit power. When multiple SUs send alarm messages, the condition remains in effect until either all calls from alarming SUs terminate, or until the transmit power of the alarming SU, measured at the SU, is a value less than the maximum transmit power. An alternative embodiment measures the bit error rate measurements from the Forward Error Correction (FEC) decoder, and holds the RCS traffic lights at "red" until the bit error rate is less than a predetermined value.

The blocking strategy of the present invention includes a method which uses the power control information transmitted from the RCS to an SU, and the received power measurements at the RCS. The RCS measures its transmit power level, detects that a maximum value is reached, and determines when to block new users. An SU preparing to enter the system blocks itself if the SU reaches the maximum transmit power before successful completion of a bearer channel assignment.

Each additional user in the system has the effect of increasing the noise level for all other users, which decreases the signal to noise ratio (SNR) that each user experiences. The power control algorithm maintains a desired SNR for each user. Therefore, in the

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absence of any other limitations, addition of a new user into the system has only a transient effect and the desired SNR is regained.

The transmit power measurement at the RCS is done by measuring either the root mean square (rms) value of the baseband combined signal or by measuring the transmit power of the RF signal and feeding it back to digital control circuits. The transmit power measurement may also be made by the SUs to determine if the unit has reached its maximum transmit power. The SU transmit power level is determined by measuring the control signal of the RF amplifier, and scaling the value based on the service type, such as plain old telephone service (POTS), FAX, or integrated services digital network (ISDN).

The information that an SU has reached the maximum power is transmitted to the RCS by the SU in a message on the Assigned Channels. The RCS also determines the condition by measuring reverse APC changes because, if the RCS sends APC messages to the SU to increase SU transmit power, and the SU transmit power measured at the RCS is not increased, the SU has reached the maximum transmit power.

The RCS does not use traffic lights to block new users who have finished ramping-up using the short codes. These users are blocked by denying them the dial tone and letting them time out. The RCS sends all 1's (go down commands) on the APC Channel to make the SU lower its transmit power. The RCS also sends either no CTCH message or a message with an invalid address which would force the FSU to abandon the access procedure and start over. The SU does not start the acquisition process immediately because the traffic lights are red.

When the RCS reaches its transmit power limit, it enforces blocking in the same manner as when an SU reaches its transmit power limit. The RCS turns off all the traffic lights on the FBCH, starts sending all 1 APC bits (go down commands) to those users who have completed their short code ramp-up but have not yet been given dial tone, and either sends no CTCH message to these users or sends messages with invalid addresses to force them to abandon the access process.

The self blocking algorithm of the SU is as follows. When the SU starts transmitting the AXCH, the APC starts its power control operation using the AXCH and

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the SU transmit power increases. While the transmit power is increasing under the control of the APC, it is monitored by the SU controller. If the transmit power limit is reached, the SU abandons the access procedure and starts over.

Although the invention has been described in terms of an exemplary embodiment,
5 it is understood by those skilled in the art that the invention may be practiced with modifications to the embodiment that are within the scope of the invention as defined by the following claims:

The Invention Claimed Is:

- 1 1. A automatic power control (APC) system for a multiple access, spread-spectrum communication system, comprising
 - 3 first and second transceivers, wherein the first transceiver transmits a forward channel information signal to the second transceiver as a forward spread-spectrum signal having a forward transmit power level, and the second transceiver transmits a reverse channel information signal to the first transceiver as a reverse spread-spectrum signal having a reverse transmit power level;
 - 8 an automatic forward power control (AFPC) system, comprising
 - 9 a) means in the second transceiver including: received signal measuring means for measuring a forward channel signal-to-noise ratio of the forward channel information signal, error generating means for generating a forward channel error signal corresponding to a difference between the measured forward channel signal-to-noise ratio and a pre-determined signal-to-noise value, and a transmitting means for transmitting the forward channel error signal as a forward error spread-spectrum signal; and
 - 17 b) means in the first transceiver including: a first receiving means for receiving the forward channel error signal from the forward error spread-spectrum signal, and a first transmit power adjustment means for adjusting the forward transmit power level of the forward spread-spectrum signal responsive to the received forward error signal, and;
 - 22 an automatic reverse power control (ARPC) system, comprising:
 - 23 a) means in the first transceiver including: received signal measuring means for measuring a reverse channel signal-to-noise ratio of the reverse channel information signal, error generating means for generating a reverse channel error signal corresponding to a difference between the measured reverse channel signal-to-noise ratio and a pre-determined signal-to-noise value, and a transmitting means for transmitting

29 the reverse channel error signal as a reverse error spread-spectrum signal;
30 and .

31 b) means in the second transceiver including: a second receiving
32 means for receiving the reverse error signal from the reverse error spread-
33 spectrum signal, and a second transmit power adjustment means for
34 adjusting the reverse transmit power level of the reverse spread-spectrum
35 signal responsive to the reverse error signal.

1 2. An APC system as set forth in claim 1 wherein each of the forward
2 error signal and the reverse error signal includes a one-bit signal which indicates
3 whether the respective difference signal is positive or negative.

1 2. An APC system as set forth in claim 1 wherein each of the forward
2 error signal and the reverse error signal includes a measure of instantaneous noise
3 in the channel.

1 2. An automatic power control (APC) system for a multiple access, spread-
spectrum communication system, comprising

3 a base station and a plurality of subscriber units, wherein the base station transmits
4 a plurality of forward channel information signals to a plurality of subscriber units as a
5 plurality of forward channel spread-spectrum signals each having a respective forward
6 transmit power level, and each of the subscriber units transmit to the base station at least
7 one reverse spread-spectrum signal having a respective reverse transmit power level and
8 at least one reverse channel spread-spectrum signal includes a reverse channel information
9 signal;

10 an automatic forward power control (AFPC) system, wherein:

11 12. a) each one of the plurality of subscriber units comprises: forward
channel signal measuring means for measuring a forward signal-to-noise
ratio of the respective forward channel information signal, forward error
generating means for generating a respective forward channel error signal
corresponding to a difference between the respective measured forward
signal-to-noise ratio and a pre-determined signal-to-noise value, and a

17 transmitting means for transmitting the respective forward channel error
18 signal as part of a respective reverse channel information signal; and

19 b) the base station comprises: a plurality of AFPC receiving means
20 for receiving the plurality of reverse channel information signals and
21 extracting the plurality of forward channel error signals from the
22 respective reverse channel information signals, and a plurality of forward
23 transmit power adjustment means for adjusting the respective forward
24 transmit power levels of the respective forward spread-spectrum signals
25 responsive to the respective forward error signals, and;

26 an automatic reverse power control (ARPC) system, wherein:

27 a) the base station comprises: a plurality of reverse signal measuring
28 means, each reverse signal measuring means for measuring a reverse
29 signal-to-noise ratio of the respective reverse channel information signal; a
30 plurality of reverse error generating means, each reverse error generating
31 means for generating a respective reverse channel error signal representing
32 a difference between the respective measured reverse channel signal-to-
33 noise ratio and a respective pre-determined signal-to-noise value; and a
34 plurality of transmitting means, each transmitting means for transmitting
35 the respective reverse channel error signal as a part of a respective forward
36 channel information signal; and

37 b) each subscriber unit comprises: an ARPC receiving means for
38 receiving a respective one of the forward channel information signals and
39 extracting the respective reverse error signal from the forward channel
40 information signal, and a subscriber transmit power adjustment means for
41 adjusting the reverse transmit power level of the respective reverse spread-
42 spectrum signal responsive to the respective reverse error signal.

1 5. An automatic forward power control (AFPC) system for a multiple access,
2 spread-spectrum communication system, comprising

3 a base station and a plurality of subscriber units, wherein the base station transmits
4 a plurality of forward channel information signals to a plurality of subscriber units as a
5 plurality of forward channel spread-spectrum signals, and each of the subscriber units
6 transmits to the base station at least one reverse spread-spectrum signal, and at least one
7 reverse channel spread-spectrum signal includes a reverse channel information signal;

8 each one of the plurality of subscriber units comprises: forward channel signal
9 measuring means for measuring a forward signal-to-noise ratio of the respective forward
10 channel information signal, forward error generating means for generating a respective
11 forward channel error signal corresponding to a difference between the respective forward
12 signal-to-noise ratio and a pre-determined signal-to-noise value, and a transmitting means
13 for transmitting the respective forward channel error signal as part of a respective reverse
14 channel information signal; and

15 the base station comprises: a plurality of AFPC receiving means for receiving the
16 plurality of reverse channel information signals and extracting the plurality of forward
17 channel error signals from the respective reverse channel information signals, and a
18 plurality of forward transmit power adjustment means for adjusting the respective forward
19 transmit power levels of each of the respective forward spread-spectrum signals
20 responsive to the respective forward error signal.

1 6. An AFPC system as set forth in claim 5 wherein the forward channel
2 error signal includes a one-bit signal which indicates whether the respective
3 difference signal is positive or negative.

1 7. An AFPC system as set forth in claim 5 wherein the forward channel
2 error signal includes a measure of instantaneous noise in the channel.

1 8. The AFPC system of claim 7, wherein each of the subscriber units further
2 comprise:

3 a system noise measuring means for measuring a system noise power level of the
4 spread-spectrum system comprising the plurality of forward spread-spectrum signals;

5 means for multiplying the difference signal by the measured system noise power
6 level to generate the forward channel error signal.

1 9. An automatic reverse power control (ARPC) system for a multiple access,
2 spread-spectrum communication system, comprising:

3 a base station and a plurality of subscriber units, wherein the base station transmits
4 a plurality of forward channel information signals to a plurality of subscriber units as a
5 plurality of forward channel spread-spectrum signals, and each ones of the subscriber
6 units transmit to the base station at least one reverse spread-spectrum signal, and at least
7 one reverse channel spread-spectrum signal includes a reverse channel information signal;

8 the base station comprises: a plurality of reverse signal measuring means, each
9 reverse signal measuring means for measuring a reverse signal-to-noise ratio of the
10 respective reverse channel information signal; a plurality of reverse error generating
11 means, each reverse error generating means for generating a respective reverse channel
12 error signal representing a difference between the respective reverse channel signal-to-
13 noise ratio and a respective pre-determined signal-to-noise value; and a plurality of
14 transmitting means, each transmitting means for transmitting the respective reverse
15 channel error signal as a part of the respective forward channel information signal; and

16 each subscriber unit comprises: an ARPC receiving means for receiving a
17 respective one of the forward channel information signals and extracting the respective
18 reverse error signal from the forward channel information signal, and a subscriber
19 transmit power adjustment means for adjusting the reverse transmit power level of the
20 respective reverse spread-spectrum signal responsive to the respective reverse error signal.

1 10. An ARPC system as set forth in claim 9 wherein the reverse channel
2 error signal includes a one-bit signal which indicates whether the respective
3 difference signal is positive or negative.

1 11. An AFPC system as set forth in claim 9 wherein the reverse channel
2 error signal includes a measure of instantaneous noise in the channel.

1 12. The ARPC system of claim 11, wherein the base station of the ARPC system
2 further comprises

3 a system noise measuring means for measuring a system noise power level of the
4 spread-spectrum system comprising the plurality of reverse spread-spectrum signals;

5 means for multiplying the difference signal by the measured system noise power
6 level to generate the reverse channel error signal.

1 13. An automatic maintenance power control (MPC) system for a multiple access,
2 spread-spectrum communication system for maintaining the initial transmit power of a
3 subscriber unit, comprising

4 a base station and a plurality of inactive subscriber units, wherein the base station
5 transmits a plurality of forward inactive channel information signals to a plurality of
6 subscriber units as a plurality of forward channel spread-spectrum signals, and each of the
7 inactive subscriber units occasionally transmits to the base station at least one reverse
8 spread-spectrum signal including a reverse channel information signal;

9 the base station comprises:

10 a) a plurality of reverse signal measuring means, each reverse signal
11 measuring means comprising: means for measuring a reverse signal-to-noise ratio
12 of the respective reverse channel information signal; a plurality of reverse error
13 generating means, each reverse error generating means for generating a respective
14 reverse channel error signal representing a difference between the respective
15 reverse channel signal-to-noise ratio and a respective pre-determined signal-to-
16 noise value;

17 b) a system noise measuring means for measuring a system noise power
18 level of the spread-spectrum system comprising: means for receiving a plurality of
19 reverse spread-spectrum signals; means for combining the received spread
20 spectrum signals with an uncorrelated despreading signal to produce a noise signal;
21 and means for measuring a power level of the noise signal to produce a system
22 noise power signal;

23 c) means for multiplying the difference signal by the system noise power
24 signal to generate the reverse channel error signal; and

25 d) a plurality of transmitting means, each transmitting means for
26 transmitting a respective reverse channel error signal as a part of a respective
27 forward channel information signal; and

28 each subscriber unit comprises an MPC receiving means for receiving a respective
29 one of the forward channel information signals and extracting the respective reverse error
30 signal from the forward channel information signal, and a subscriber transmit power
31 adjustment means for adjusting the reverse transmit power level of the respective reverse
32 spread-spectrum signal responsive to the respective reverse error signal.

1 14. The automatic maintenance power control (MPC) system of claim 29, further
2 comprising a plurality of active subscriber units each of which transmits substantially
3 continuous active information signals and wherein the plurality of reverse spread-spectrum
4 signals includes the plurality of active information signals.

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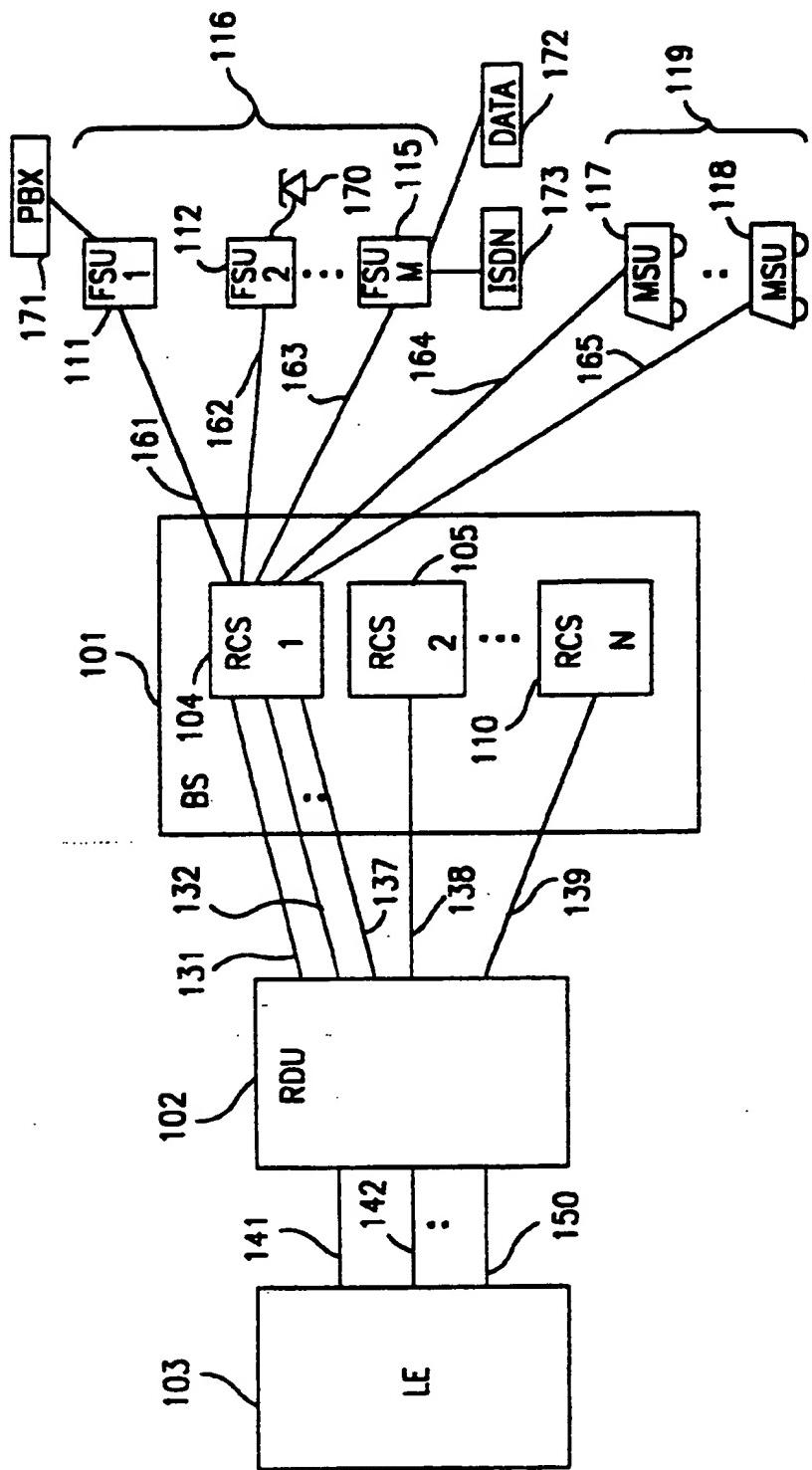


FIG. I

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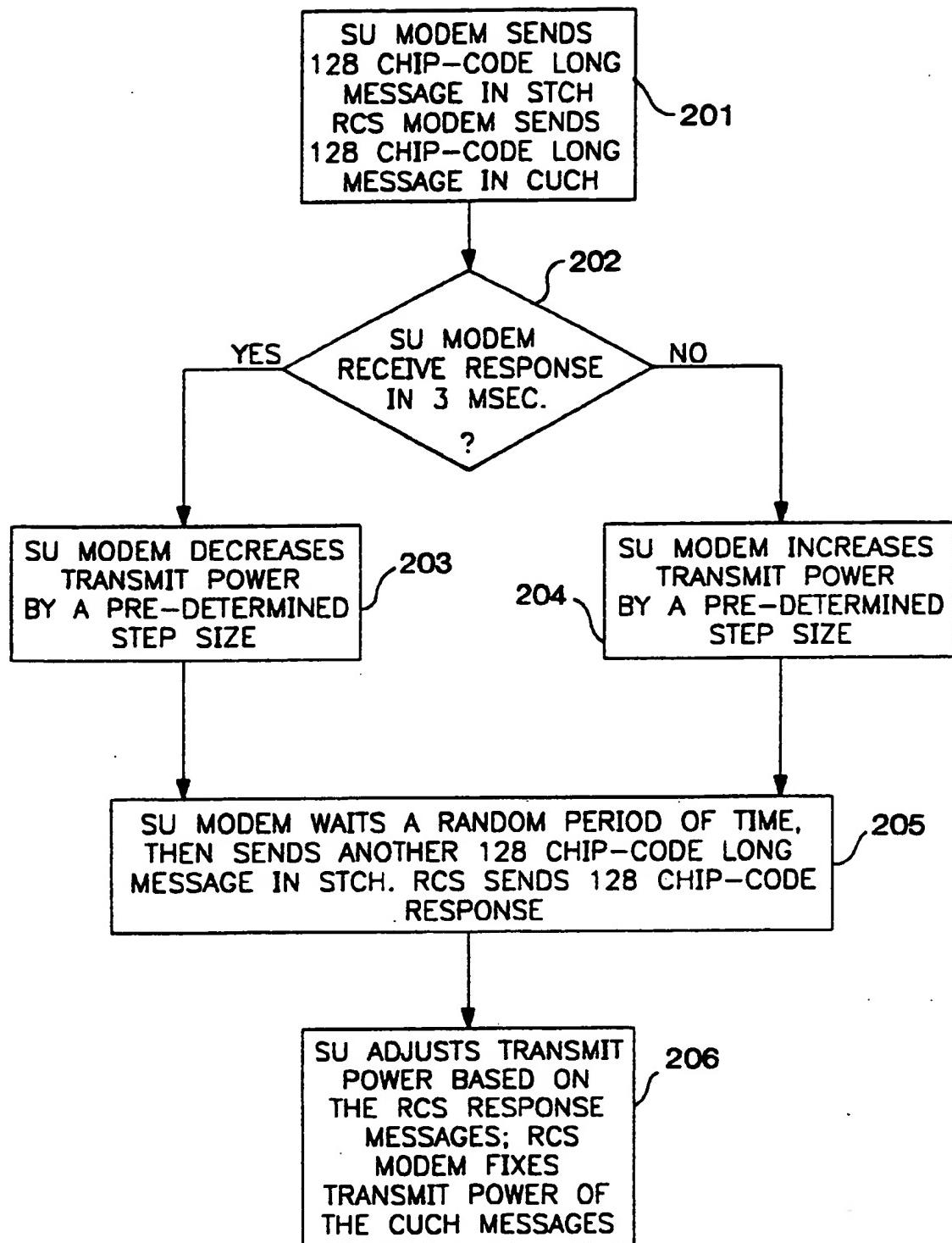


FIG. 2

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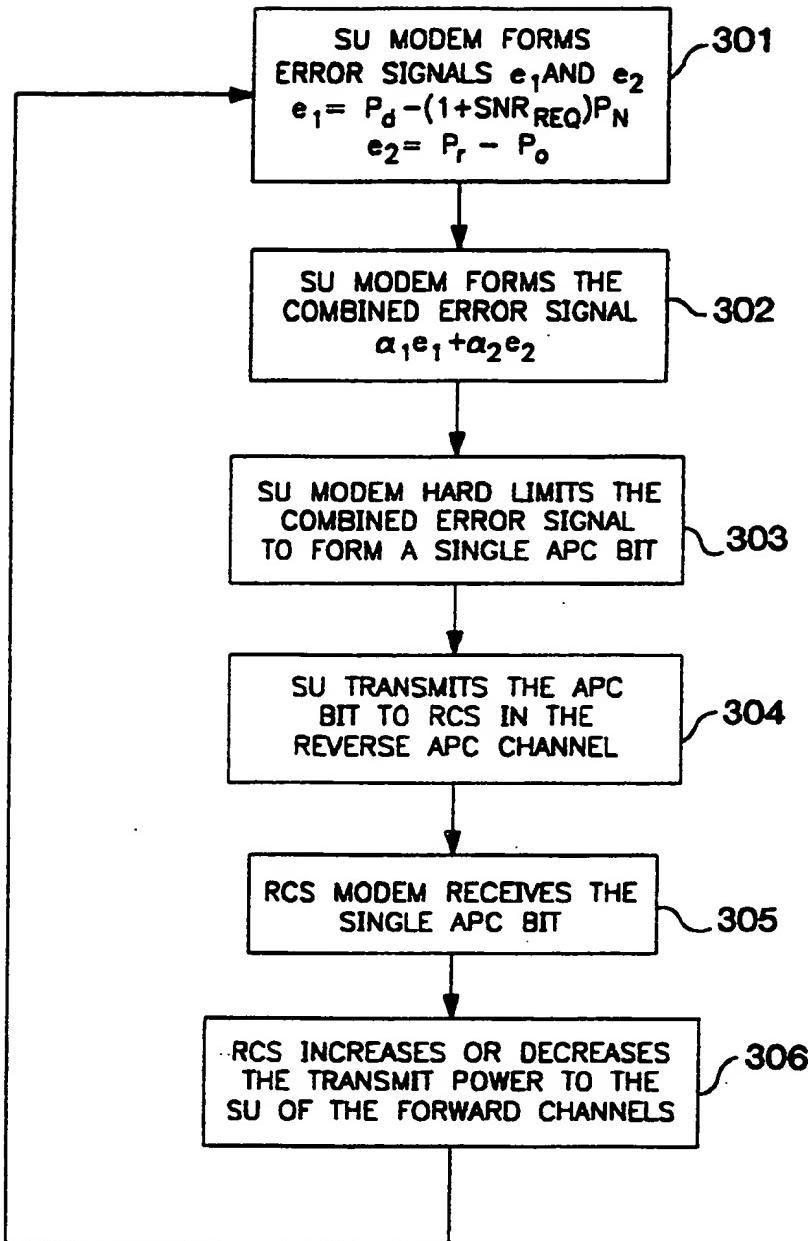


FIG. 3

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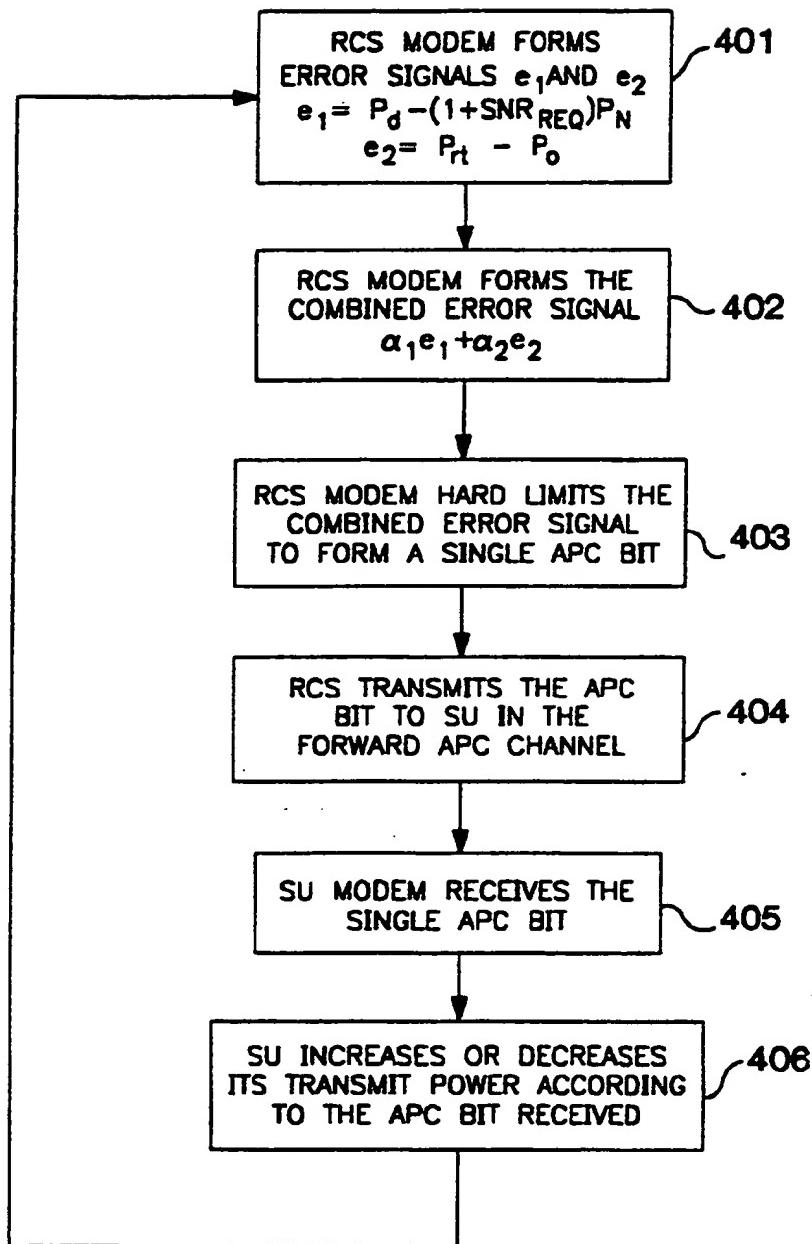


FIG. 4

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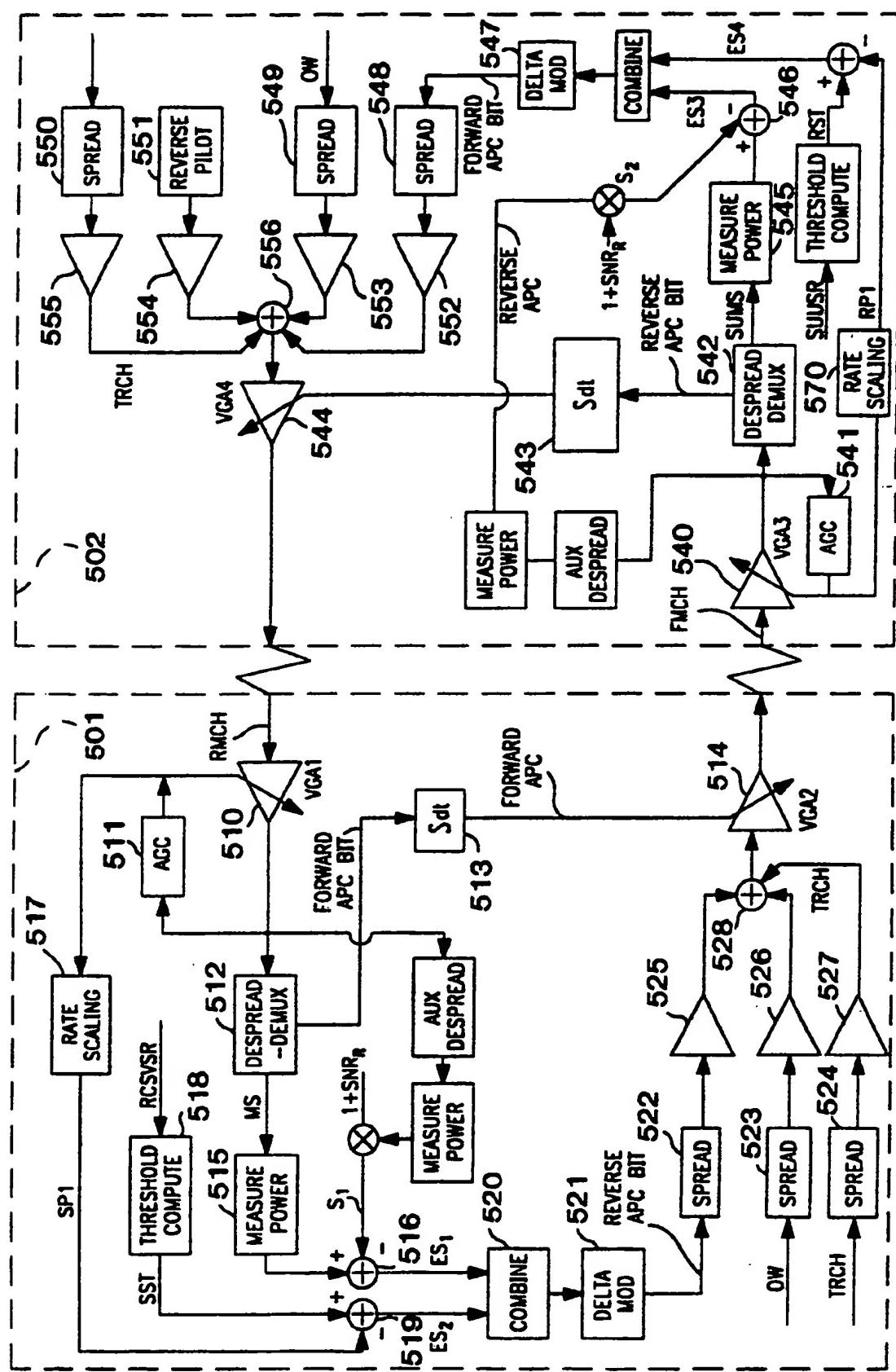


FIG. 5

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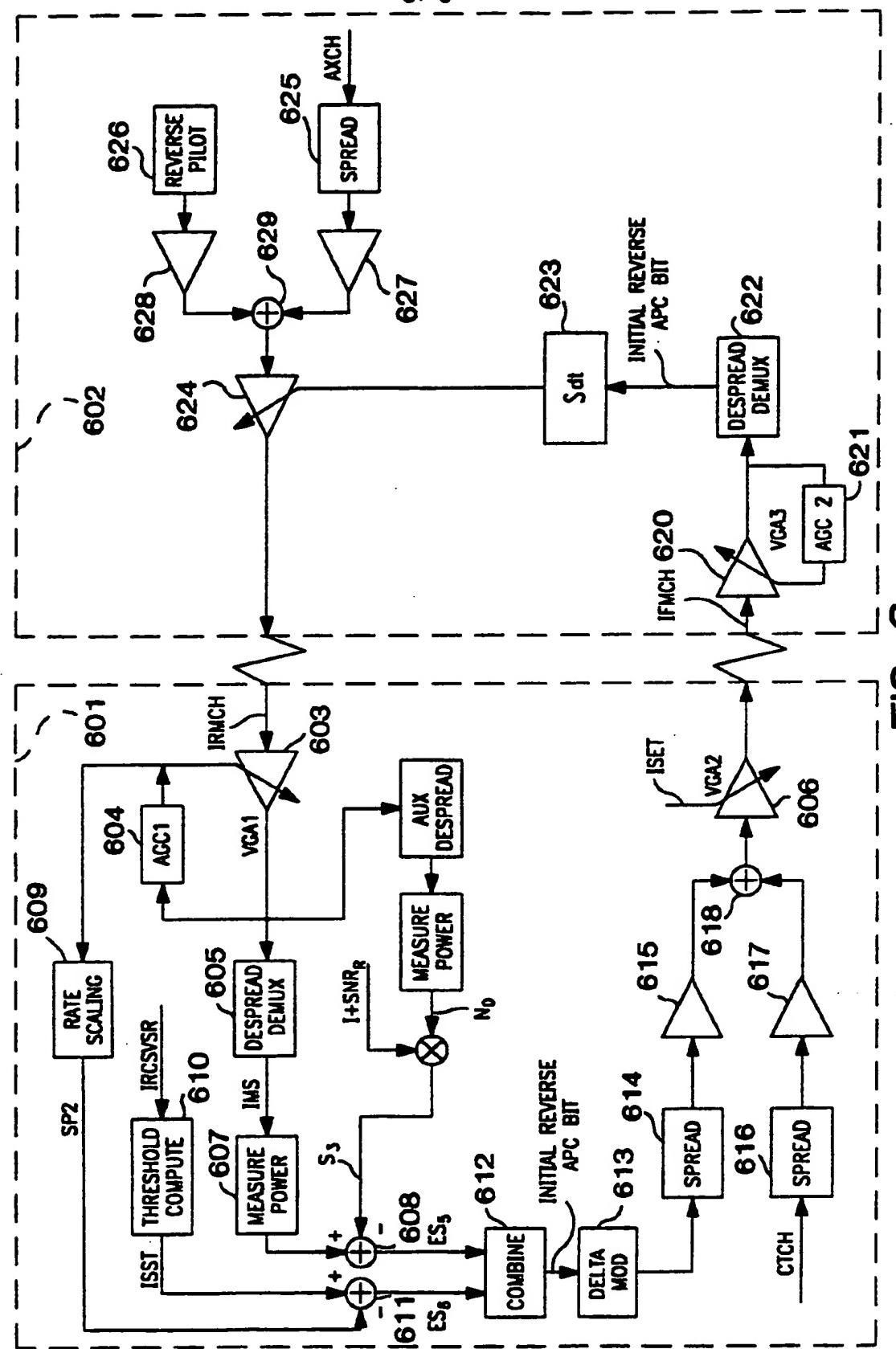


FIG. 6